

# Simulation-based large-scale structure inference

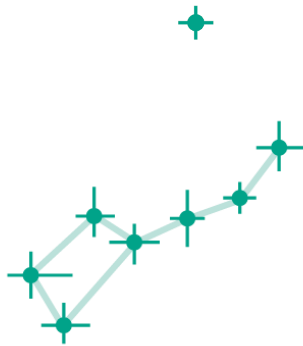
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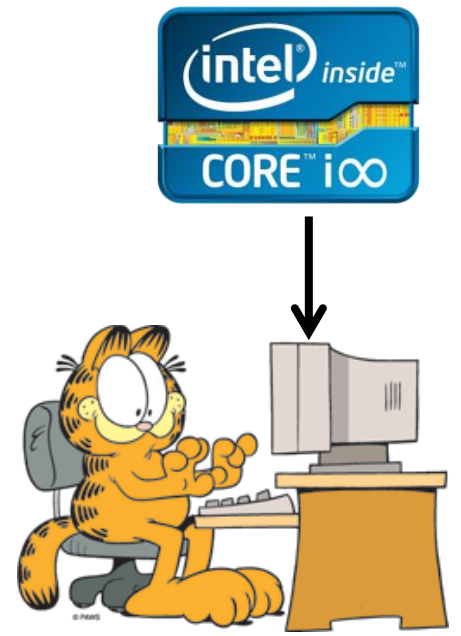
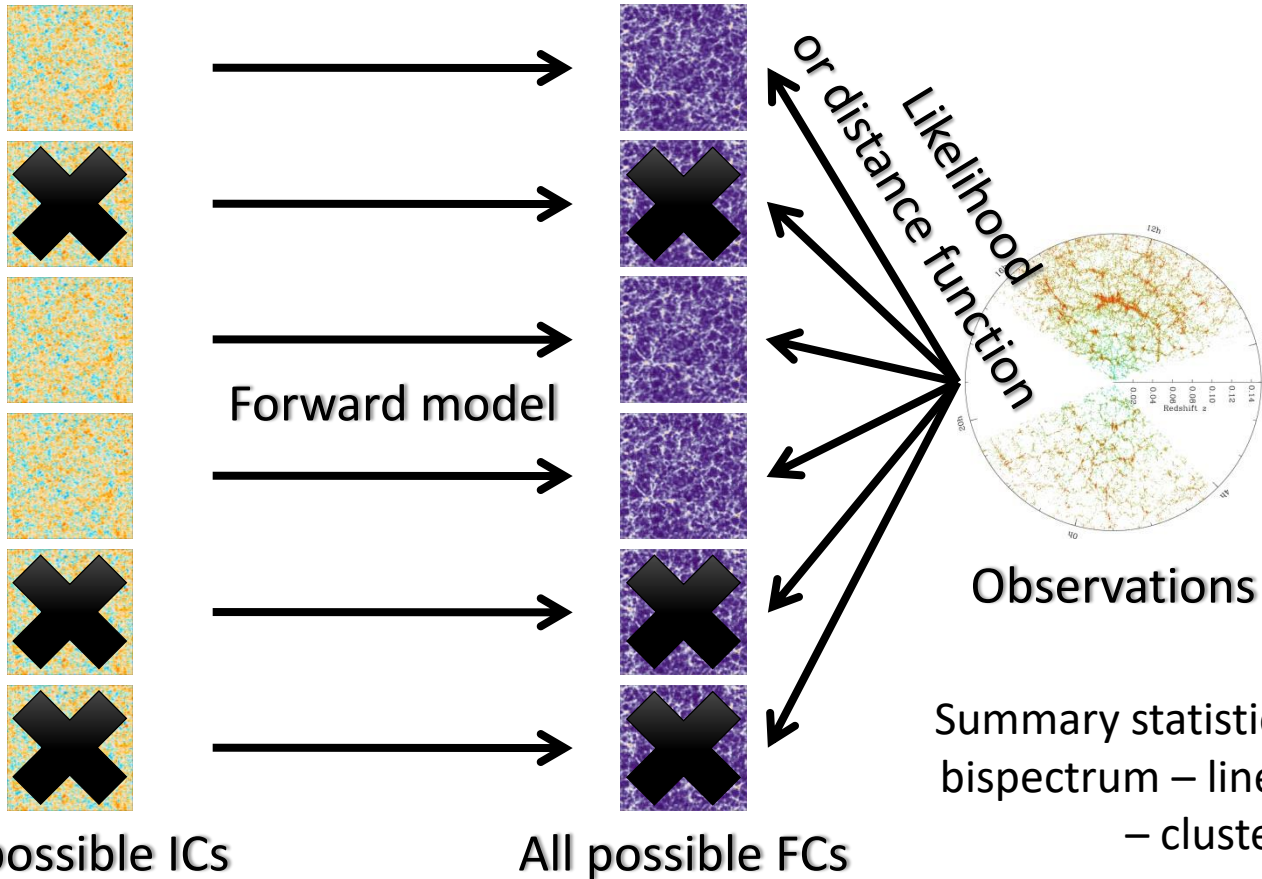
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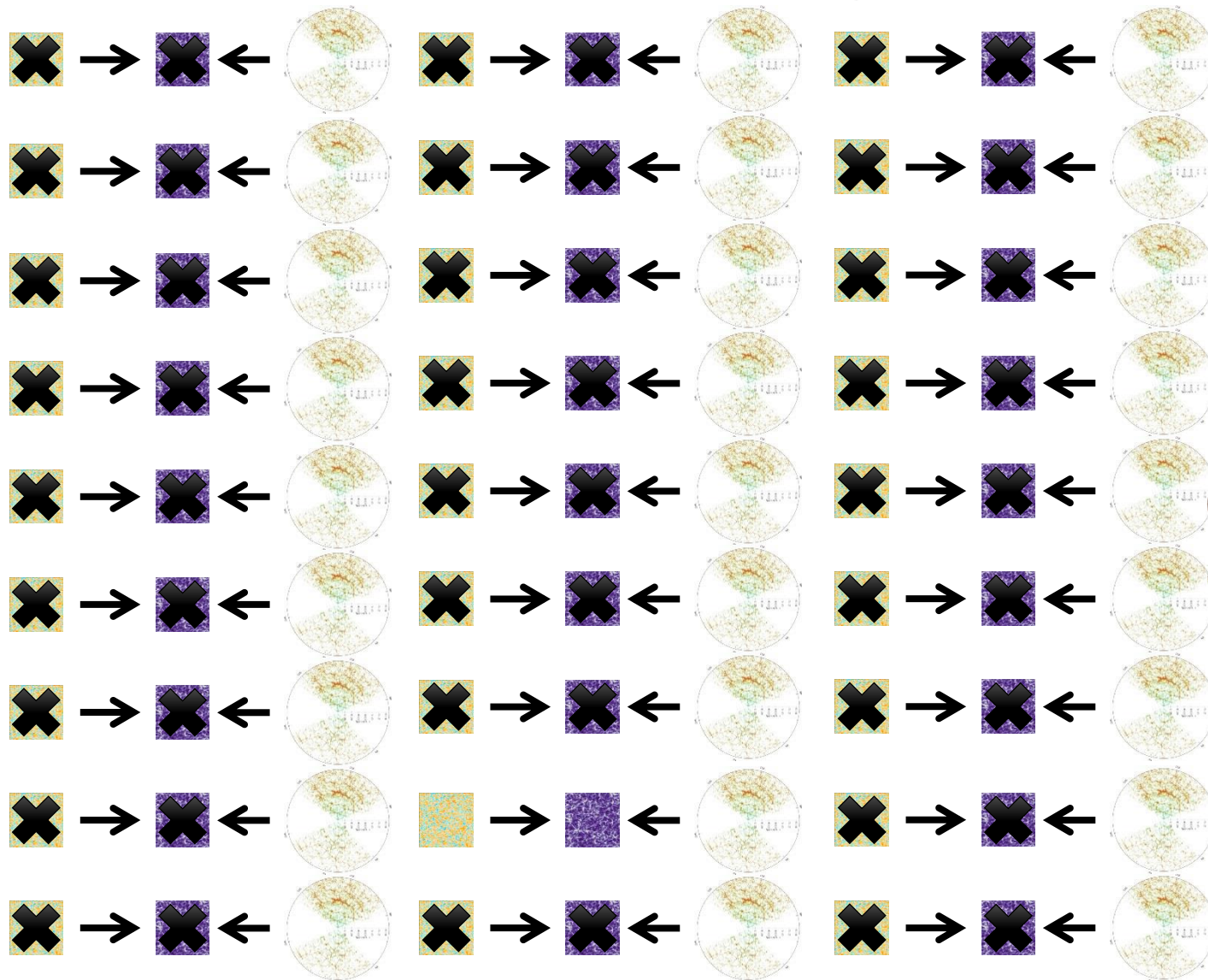
# Bayesian forward modeling: the ideal scenario

Forward model = N-body simulation + Halo occupation +  
Galaxy formation + Feedback + ...



Summary statistic = power spectrum –  
bispectrum – line correlation function  
– clusters – voids...

# Bayesian forward modeling: the challenge



$d \approx 10^7$

# LIKELIHOOD-FREE LARGE-SCALE STRUCTURE INFERENCE

# Approximate Bayesian Computation (ABC)

- Statistical inference for models where:
  1. The likelihood function is intractable
  2. Simulating data is possible
- **General idea:** find parameter values for which the distance between simulated data and observed data is small

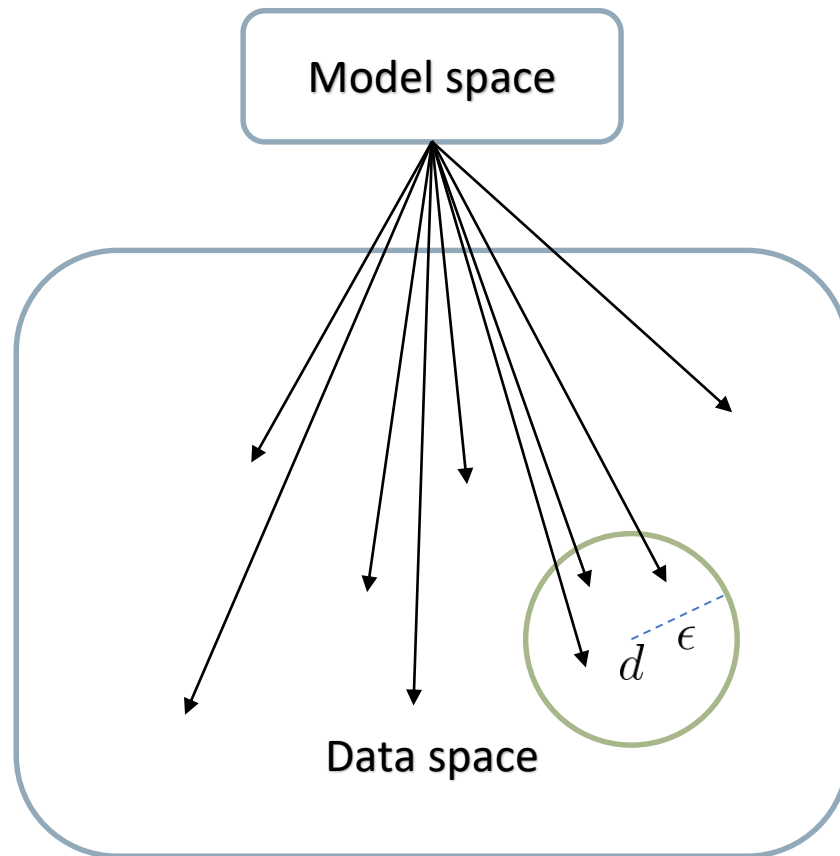
$$p(\theta|d) \implies p(\theta|\tilde{d}) \quad \text{where } d(\tilde{d}(\theta), d) \text{ is small}$$

- **Assumptions:**
  - Only a small number of parameters are of interest
  - But the process generating the data is very general: a noisy non-linear dynamical system with an unrestricted number of hidden variables

# Likelihood-free rejection sampling

- Iterate many times:
  - Sample  $\theta$  from a proposal distribution  $q(\theta)$
  - Simulate  $\tilde{d}(\theta)$  according to the data model
  - Compute distance  $d(\tilde{d}(\theta), d)$  between simulated and observed data
  - Retain  $\theta$  if  $d(\tilde{d}(\theta), d) \leq \epsilon$ , otherwise reject
- Effective likelihood approximation:

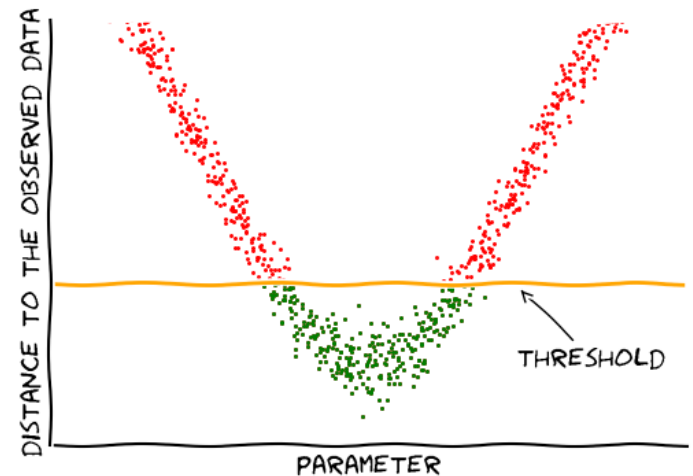
$$L(\theta) \approx \frac{1}{N} \sum_{i=1}^N \mathbb{I} \left( d(\tilde{d}(\theta), d) \leq \epsilon \right)$$



$\epsilon$  can be adaptively reduced  
(Population Monte Carlo)

# Why is likelihood-free rejection so expensive?

1. It rejects most samples when  $\epsilon$  is small
2. It does not make assumptions about the shape of  $L(\theta)$
3. It uses only a fixed proposal distribution, not all information available
4. It aims at equal accuracy for all regions in parameter space



$$L(\theta) \approx \frac{1}{N} \sum_{i=1}^N \mathbb{I} \left( d(\tilde{d}(\theta), d) \leq \epsilon \right)$$

# Proposed solution

## Bayesian optimisation for likelihood-free inference (BOLFI)

1. It rejects most samples when  $\epsilon$  is small

➡ Don't reject samples: learn from them!

2. It does not make assumptions about the shape of  $L(\theta)$

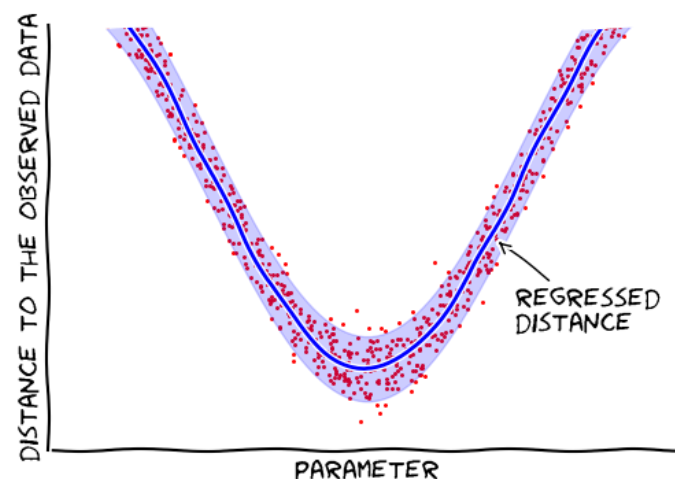
➡ Model the distances, assuming the average distance is smooth

3. It uses only a fixed proposal distribution, not all information available

➡ Use Bayes' theorem to update the proposal of new points

4. It aims at equal accuracy for all regions in parameter space

➡ Prioritize parameter regions with small distances to the observed data



Related work in cosmology:

[Alsing & Wandelt 2017, arXiv:1712.00012](#)

(data compression for ABC)

[Alsing, Wandelt & Feeney 2018, arXiv:1801.01497](#)

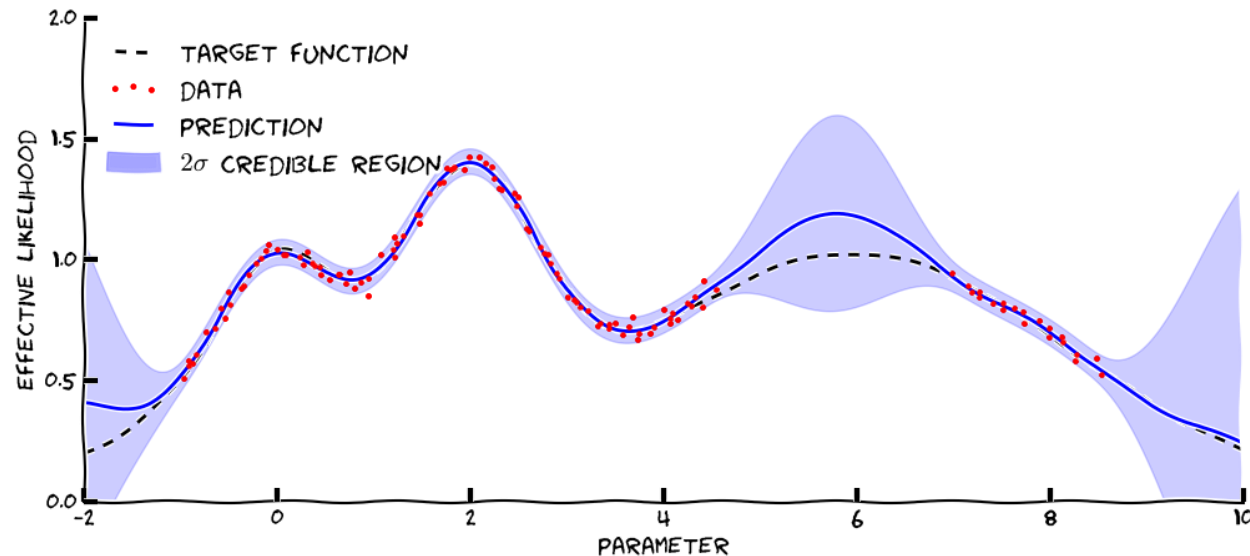
(density estimation for ABC – DELFI)

[Enzi, Jasche & FL 2018, to be submitted](#)

(ABC with linear expansion of the effective likelihood)



# Regressing the effective likelihood (points 1 & 2)



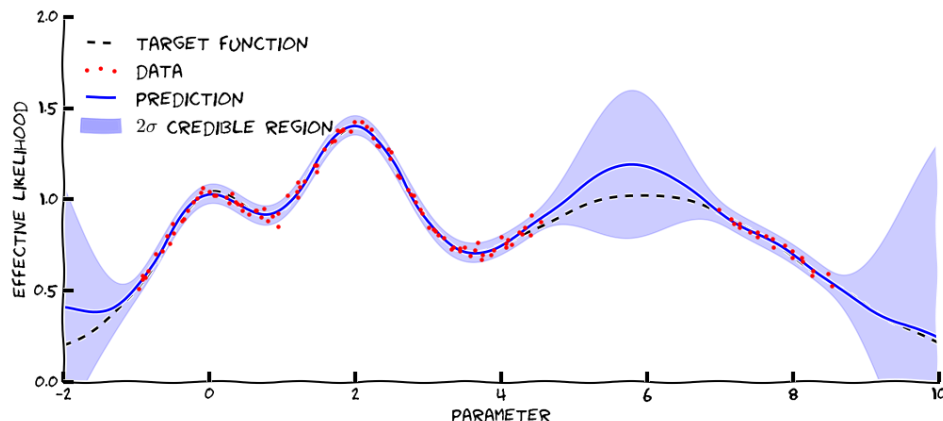
1. “It rejects most samples when  $\epsilon$  is small”

- Keep all values  $(\theta_i, d_i)$   $d_i = d(\tilde{d}(\theta_i), d)$

2. “It does not make assumptions about the shape of  $L(\theta)$ ”

- Model the conditional distribution of distances given this training set

# Gaussian process regression (a.k.a. kriging)



## • Why?

- It is a **general purpose regressor**: it will be able to deal with a large variety of complex/non-linear features of likelihood functions.
- It provides not only a prediction, but also the **uncertainty of the regression**.
- It allows to **extrapolate** in regions where we have no data points.

$$p(\mathbf{f}|\mathbf{X}) \propto \exp \left[ -\frac{1}{2} \sum_{mn} (f(\mathbf{x}_m) - \mu(\mathbf{x}_m))^T K(\mathbf{x}_m, \mathbf{x}_n) (f(\mathbf{x}_n) - \mu(\mathbf{x}_n)) \right]$$

$$K(\mathbf{x}_m, \mathbf{x}_n) = \underbrace{C_1}_{K_C(C_1)} \times \underbrace{\exp \left[ -\frac{1}{2} \left( \frac{\mathbf{x}_m - \mathbf{x}_n}{C_2} \right)^2 \right]}_{K_{\text{RBF}}(C_2)} + \underbrace{C_3 \delta_{\text{K}}^{mn}}_{K_{\text{GN}}(C_3)}$$

The prediction and uncertainty for a new point is:

$$p(f_* | \mathbf{x}_*, \mathbf{X}, \mathbf{f}) \propto \exp \left[ -\frac{1}{2} \left( \frac{f_* - \alpha(\mathbf{x}_*)}{\sigma(\mathbf{x}_*)} \right)^2 \right]$$

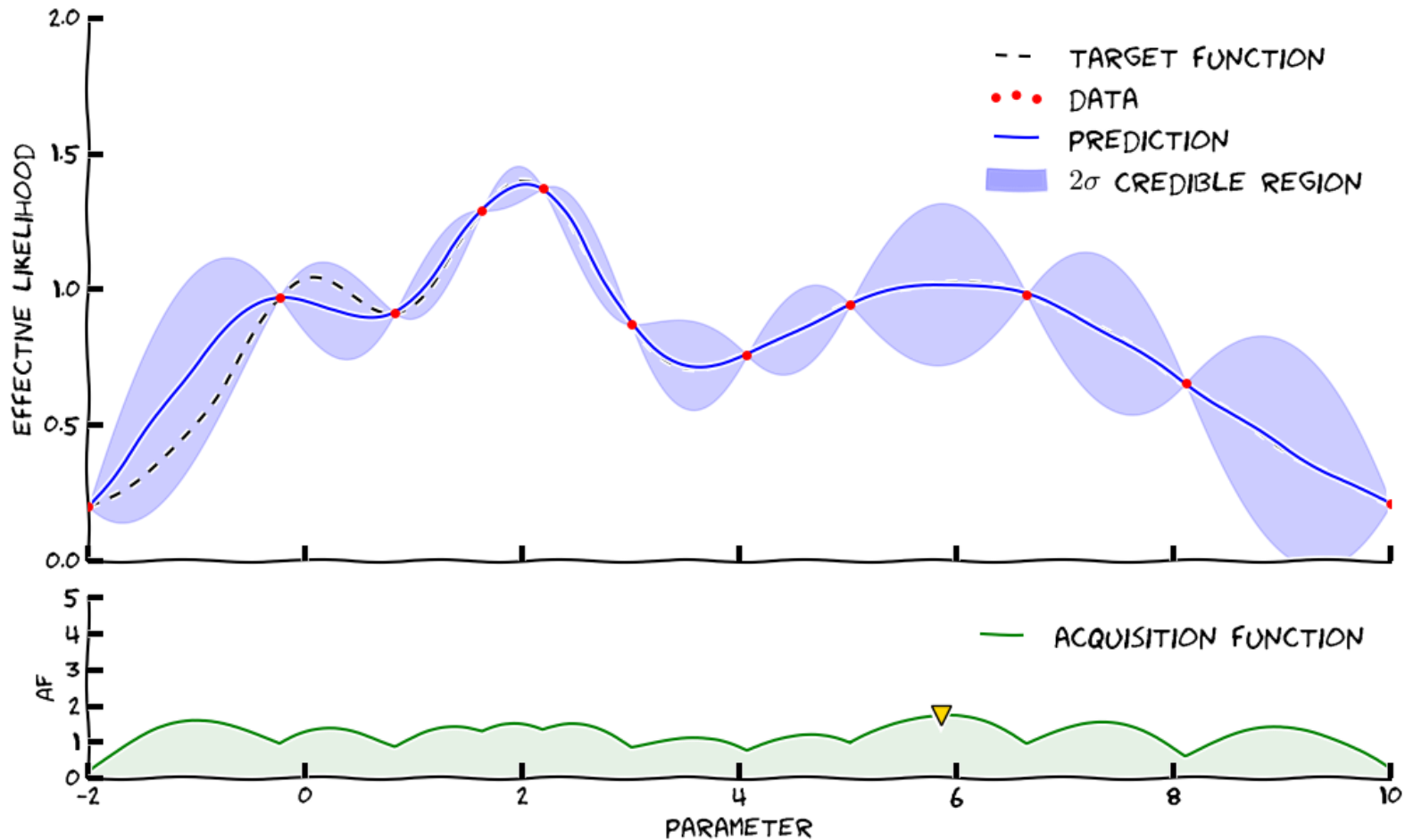
$$\alpha(\mathbf{x}_*) = \mu(\mathbf{x}_*) + K(\mathbf{x}_*, \mathbf{x}_m)^T K^{-1}(\mathbf{x}_m, \mathbf{x}_n) (\mathbf{f} - \mu(\mathbf{X}))_n$$

$$\sigma(\mathbf{x}_*)^2 = K(\mathbf{x}_*, \mathbf{x}_*) - K(\mathbf{x}_*, \mathbf{x}_m)^T K^{-1}(\mathbf{x}_m, \mathbf{x}_n) K(\mathbf{x}_*, \mathbf{x}_n)$$

Hyperparameters  $C_1, C_2, C_3$  are automatically adjusted during the regression.

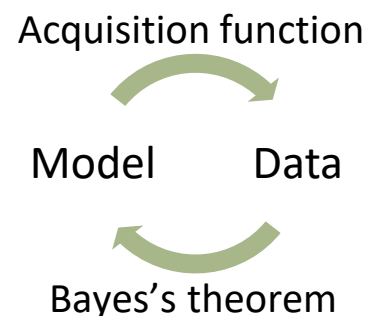
# Data acquisition

STEP 11



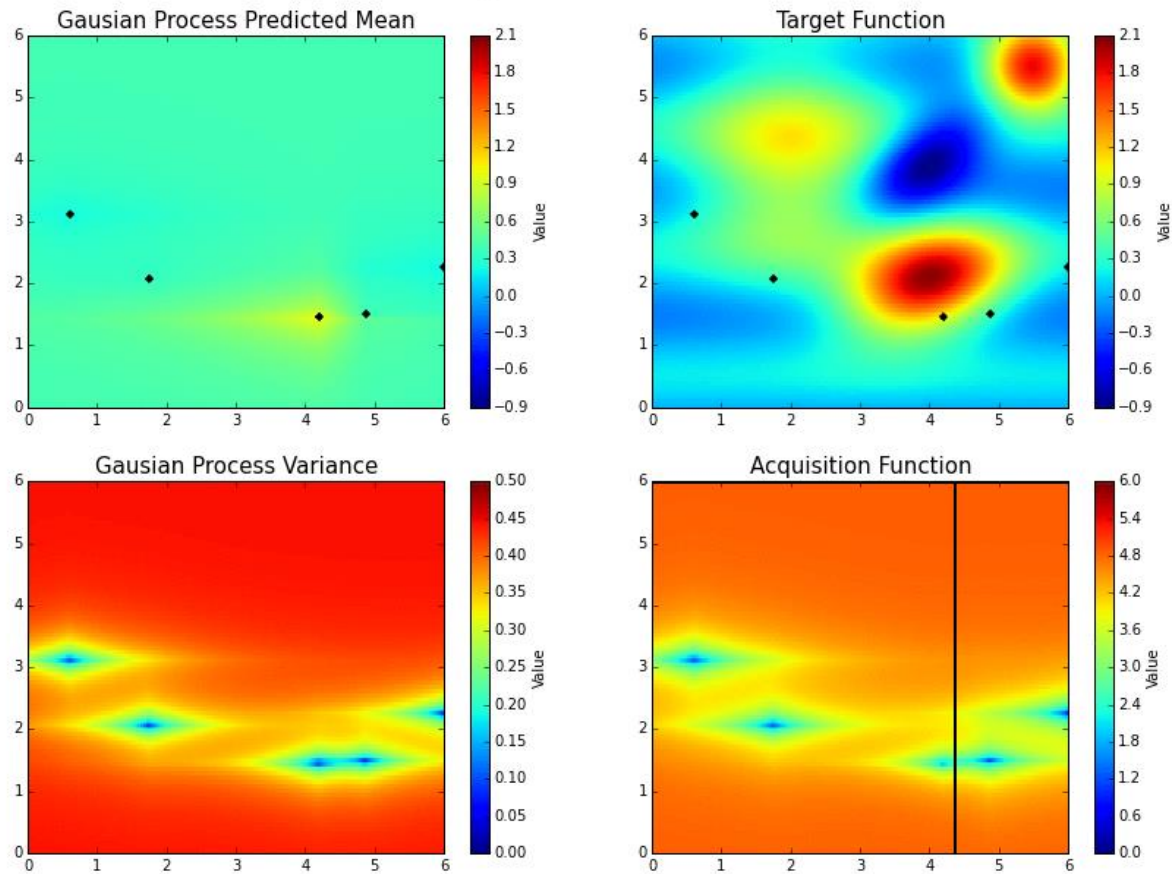
# Data acquisition (points 3 & 4)

3. “It uses only a fixed proposal distribution, not all information available”
  - Samples are obtained from sampling an **adaptively-constructed proposal distribution**, using the regressed effective likelihood
4. “It aims at equal accuracy for all regions in parameter space”
  - The **acquisition function** finds a compromise between exploration (trying to find new high-likelihood regions) & exploitation (giving priority to regions where the distance to the observed data is already known to be small)
  - **Bayesian optimisation** (decision making under uncertainty) can then be used



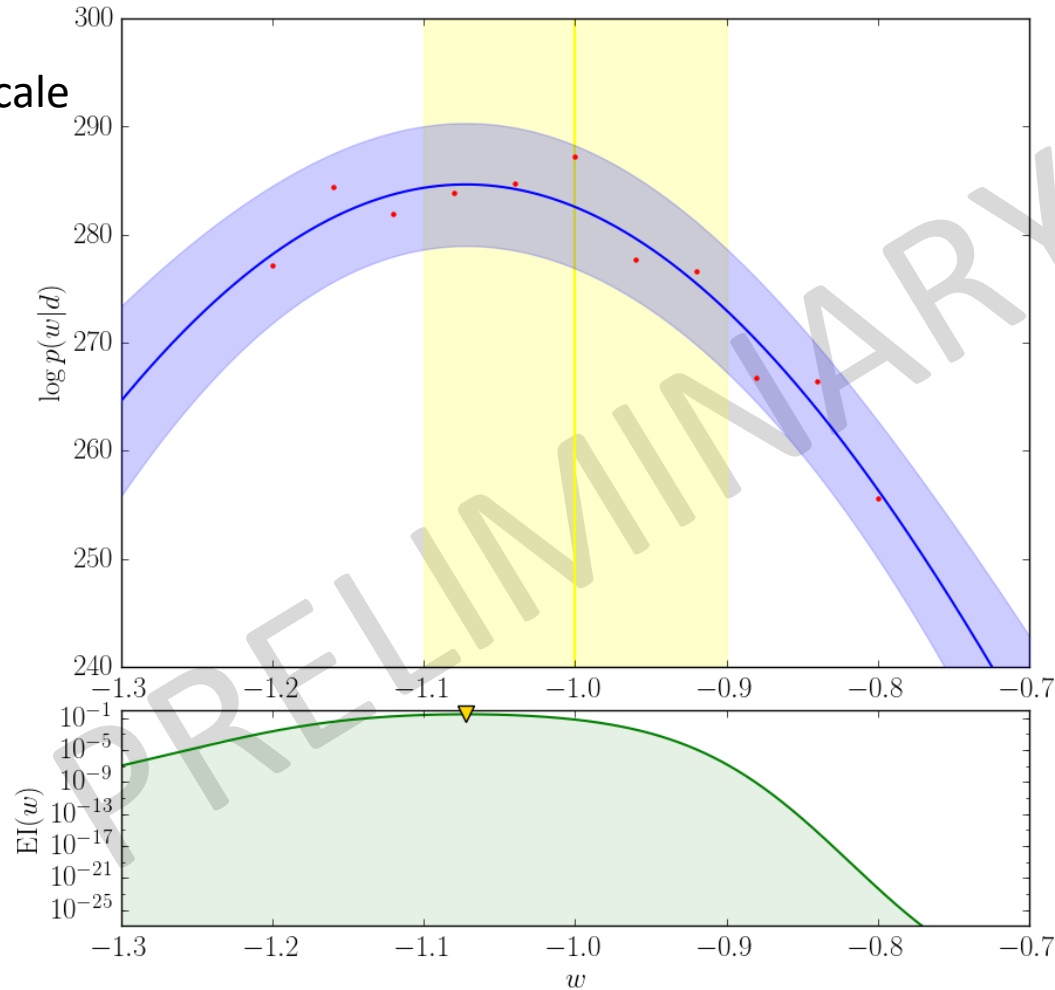
# In higher dimension...

## Bayesian Optimization in Action

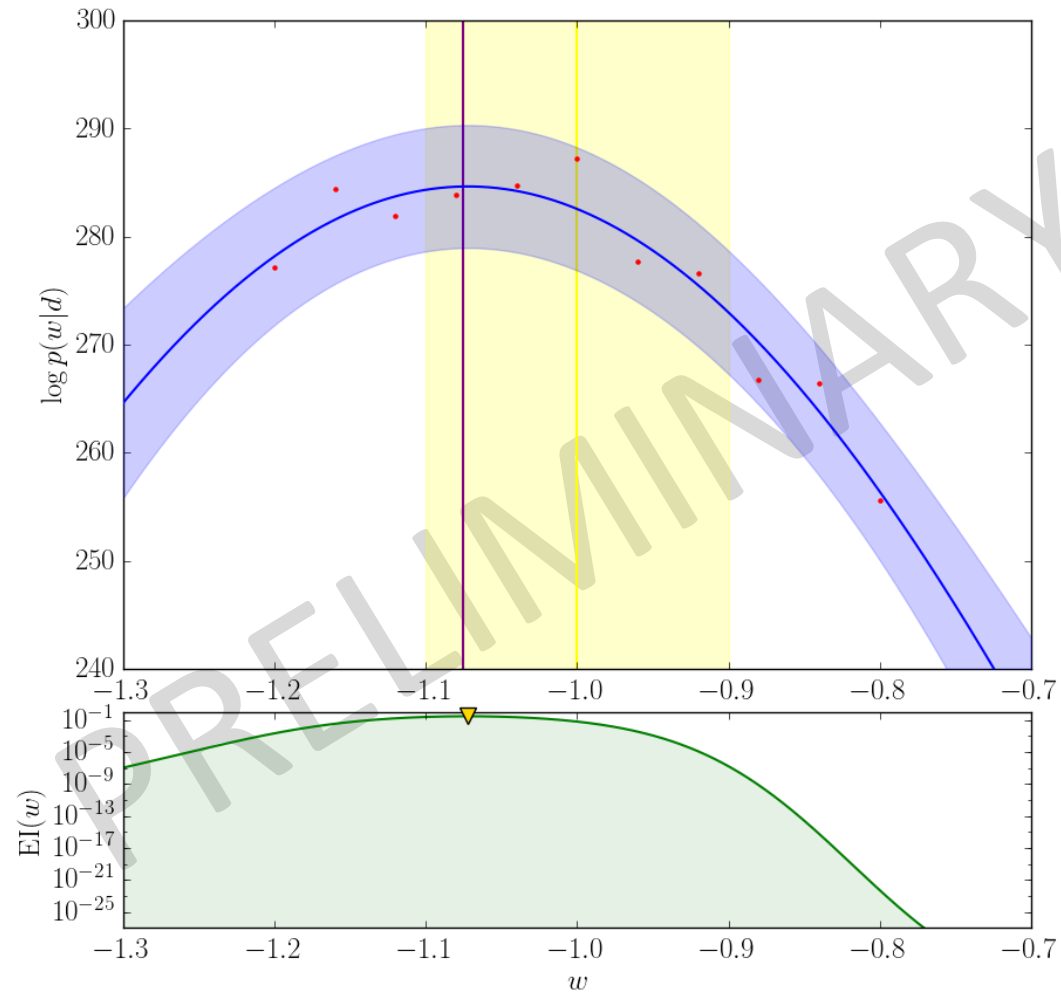


# Likelihood-free large-scale structure inference

- 1100 large-scale structure simulations using COLA
- $\approx 10^7$  hidden variables



# Likelihood-free large-scale structure inference



This proof-of-concept has been performed  
completely blindly.

# Summary

- A likelihood-free method for models where the likelihood is intractable but simulating is possible:

## Regression of the distance + Bayesian optimisation

- Number of required simulations reduced by several orders of magnitude.
- The approach will allow to **ask targeted questions to cosmological data**, including all relevant physical and observational effects.
- Optimisation of the data model using **tCOLA + sCOLA**
  - Enormous parallelisation potential for dark matter simulations.
  - Further speed-up expected for realistic synthetic observations.