

Bayesian model comparison.

Basics:

$$B_{12} = \frac{p(d|\mathcal{M}_1)}{p(d|\mathcal{M}_2)}$$

Bayes factor.

assumes implicitly $p(\mathcal{M}_1) = p(\mathcal{M}_2)$

ratio of evidences. (\neq ratio of likelihoods) in frequentist stats.

$$p(d|\mathcal{M}_1) = \int p(d|\theta, \mathcal{M}_1) p(\theta|\mathcal{M}_1) d\theta$$

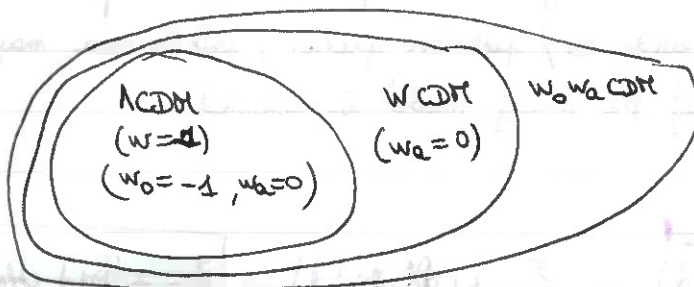
evidence = marginal likelihood \mathcal{M}_1

param space of likelihood prior.

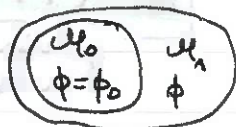
Nested models and the Savage-Dickey Density Ratio (SDDR):

Example:

nested models.



suppose



ϕ subset of all params ψ .

$$B_{01} = \frac{p(d|\mathcal{M}_0)}{p(d|\mathcal{M}_1)}$$

$$p(d|\mathcal{M}_0) = \int p(d|\psi, \mathcal{M}_0) p(\psi|\mathcal{M}_0) d\psi$$

continuity condition. $p(\psi|\mathcal{M}_0) = p(\psi|\phi=\phi_0, \mathcal{M}_1)$.

$$\begin{aligned} \Rightarrow p(d|\mathcal{M}_0) &= \int p(d|\psi, \phi=\phi_0, \mathcal{M}_1) p(\psi|\phi=\phi_0, \mathcal{M}_1) d\psi = p(d|\phi=\phi_0, \mathcal{M}_1) \\ &= \frac{p(\phi=\phi_0|d, \mathcal{M}_1) p(d|\mathcal{M}_1)}{p(\phi=\phi_0|\mathcal{M}_1)} \end{aligned}$$

$$\Rightarrow \boxed{B_{01} = \frac{p(\phi=\phi_0|d, \mathcal{M}_1)}{p(\phi=\phi_0|\mathcal{M}_1)}} \text{ (SDDR). These are usually low-d probabilities.}$$

Bayesian model selection as a decision analysis

$\{\mathcal{M}_k\}_{1 \leq k \leq Nm}$: set of models

$\{a_k\} = \{\text{"selecting } \mathcal{M}_k\}\}_{1 \leq k \leq Nm}$: set of actions.

⇒ Bayesian decision theory says: take action a^* :

$$a^* = \operatorname{argmax}_a U(a_k | d)$$

$$U(a_k | d) = \sum_{k'} G(a_k | \mathcal{M}_{k'}) \pi(\mathcal{M}_{k'} | d)$$

with this formulation, instead of the posterior odds of pairs of models,

$$P_{k|k'} = \pi(\mathcal{M}_k | d) / \pi(\mathcal{M}_{k'} | d), \text{ one can quote the ratios}$$

$$U_{k|k'} = U(\mathcal{M}_k | d) / U(\mathcal{M}_{k'} | d) \equiv \text{Bayes utility factors.}$$

Simplest choice: 0-1 gain functions: $G(a_k | \mathcal{M}_k) = \delta_{kk'} \Rightarrow U(a_k | \mathcal{M}_k) = \pi(\mathcal{M}_k | d)$.

$P_{k|k'} = U_{k|k'}$, we are back to usual Bayesian model comparison.

More generally: one may want to favour models for reasons that are not encoded in their evidences / posterior proba., and/or one may not want to "lose everything" if the wrong model is selected.

Model averaging.

$$\pi(\theta | d) = \sum_k \pi(\theta | \mathcal{M}_k | d) = \sum_k \underbrace{\pi(\theta | d, \mathcal{M}_k)}_{\text{posterior of } \theta \text{ in } \mathcal{M}_k} \underbrace{\pi(\mathcal{M}_k | d)}_{\text{posterior of } \mathcal{M}_k}$$

in particular:

$$E(\theta | d) = \sum_k E(\theta | d, \mathcal{M}_k) \pi(\mathcal{M}_k | d)$$

$$\text{Var}(\theta | d) = \sum_k \left[\text{Var}(\theta | d, \mathcal{M}_k) + E(\theta | d, \mathcal{M}_k)^2 \right] \pi(\mathcal{M}_k | d) - E(\theta | d)^2$$

for cases where all the $\pi(\mathcal{M}_k)$ are equal:

$$\pi(\theta | d) \propto \sum_k \underbrace{\pi(\theta | d, \mathcal{M}_k)}_{\text{posterior of } \theta \text{ in } \mathcal{M}_k} \underbrace{\pi(d | \mathcal{M}_k)}_{\text{evidence of } \mathcal{M}_k}$$

Model selection with insufficient summary statistics.

within a model $S(d)$ is sufficient for parameter θ if and only if:

$$\pi(\theta | S(d)) = \pi(\theta | d, S(d)) \Leftrightarrow \pi(d | S(d), \theta) = \pi(d | S(d)).$$

$$= f(\theta | d)$$

$$B_{12} = \frac{\pi(d | \mathcal{M}_1)}{\pi(d | \mathcal{M}_2)} = \frac{\pi(d | S(d), \mathcal{M}_1) \pi(S(d) | \mathcal{M}_1)}{\pi(d | S(d), \mathcal{M}_2) \pi(S(d) | \mathcal{M}_2)} = \frac{\pi(d | S(d), \mathcal{M}_1)}{\pi(d | S(d), \mathcal{M}_2)} \frac{B_{12}^S}{B_{12}^S}$$

true Bayes factor for full data

not bounded, a priori!

approximate Bayes factor from statistics summary.

$S(d)$ is sufficient for comparing \mathcal{M}_1 and \mathcal{M}_2 if and only if

$$\pi(d | S(d), \mathcal{M}_1) = \pi(d | S(d), \mathcal{M}_2) \quad (\Leftrightarrow B_{12} = B_{12}^S)$$

Sufficiency for $\mathcal{M}_1, \mathcal{M}_2$ or even both does not imply sufficiency for comparing \mathcal{M}_1 and \mathcal{M}_2 .

Danger in part. for ABC: B_{12}^S can be biased, and the approximation error unrelated to the computational effort (Robert et al. 2011)

(Diebolt et al 2011)